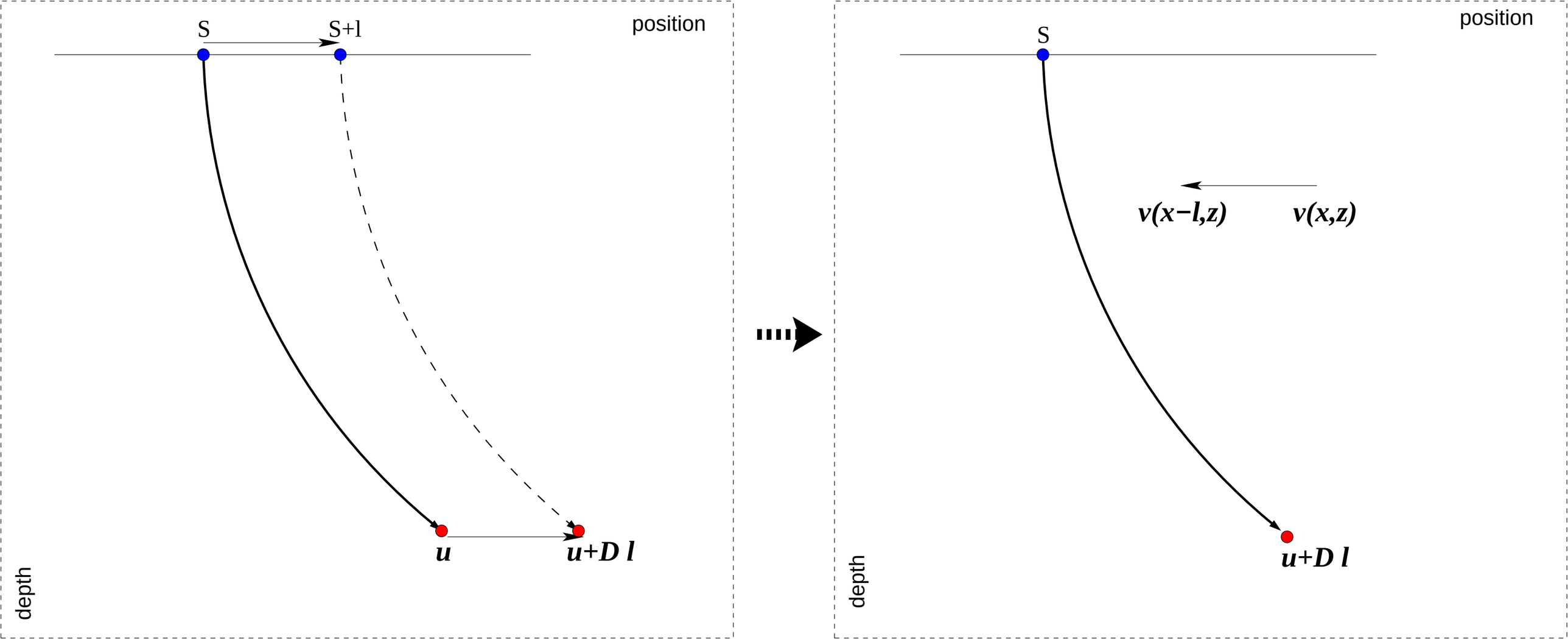
S
S+l
position
u
u+D l
depth
S
position
v(x−l,z)
v(x,z)
u+D l
depth